

An AI Approach to Locate Cluster Centre in Wireless Sensor Networks

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Abstract—Wireless sensor networks, which consist of a immense number of sensor nodes have emerged as an inevitable, effective and important technology in telecommunication field. Sensor nodes can be deployed in any harsh environment for health monitoring, industrial monitoring, structural analysis, detecting intruders etc. Since it works in battery, the major challenge is to improve the lifetime of sensor node by effectively reducing energy consumption. Otherwise, it is very difficult to frequently replace the sensor nodes. For this, many routing protocols have been proposed in which cluster based routing protocol plays a vital role. In cluster based routing protocol, entire WSN network is divided into several groups or clusters. Then for each cluster a cluster head (CH) is selected. Sensors sense the data and forward it to their corresponding CH where the entire data of that cluster get aggregated and transmitted to base station (BS). The clustering technique offers more benefit than existing flat based routing protocols since the data is transmitted via CH rather than directly by each sensor nodes. Thus the selection of CH is very important. Here we proposed a method named firefly based nearest neighbor chain algorithm to select the centre of cluster based on which CH selection can be done.

Index Terms—WSN; energy consumption; cluster based routing protocol; CH selection.

I. INTRODUCTION

Developments in electronics field paved the way for introducing low cost, small sized and easily deployable sensors which became an important computing technology for environment monitoring. WSN which consists of a huge number of sensor nodes is not only a simple sensing network but also storage, processing and efficient communication network. It provides services in healthcare, structure and environment monitoring [1]. Sensor nodes collect data and send to BS via CH. It is tedious task to frequently replace the battery once a sensor node is deployed. So it is necessary to find out a technique that will reduce the energy consumption of sensor nodes for improving the network life time.

Based on network structure, the routing protocols in WSN are classified in to flat based routing protocol and cluster based routing protocol [2]. In flat based routing protocol, each sensor node independently forwards the data to BS irrespective of its position. But in cluster based routing method, data sensed by each sensor node is

collected by corresponding CH and then forwarded to BS. This will reduce the overall communication overhead and energy consumption.

Some protocols adopt single hop communication whereas others adopt multihop communication to transfer the data to BS [3]. CH selection is an important step in cluster based routing protocol. Normally CH is selected based on energy, centrality etc. It is the CH which aggregates the data in the network and forwarded the same to the destination. It is better to select a node located at the centre of cluster as CH. This is because; other nodes can communicate with this cluster head with minimal energy.

Here in this paper, we are integrating nearest neighbor chain algorithm with firefly algorithm to find the centre of clusters with the most optimal neighbour nodes present. For this we have to calculate the distance between each sensor nodes and attractiveness of firefly. Using an equation we can calculate movement of firefly which is attracted to another firefly. Algorithm works for several iterations. Distance and movement of the firefly can be updated at each iteration.

This paper is organized as follows: Section II describes related works that inspired and motivates us to this work. Section III explains proposed firefly based nearest neighbour algorithm to find the centre of cluster and section IV concludes the paper with future enhancements.

II. RELATED WORK

Different cluster based routing protocols with energy efficiency have been proposed by researches to improve and enhance the network longevity of wireless sensor network.

The first clustering protocol named Low Energy Adaptive Clustering Hierarchy (LEACH) [4] protocol uses a distributed clustering algorithm in which CHs are selected based on a predetermined probability. Each other nodes select their cluster based on the distance to CH. But leach does not provide a uniform distribution of cluster head and sometimes same nodes became CH in more than one round repeatedly. This will abruptly reduce the energy of that particular node and creates an energy hole. Hybrid Energy-Efficient Distributed clustering (HEED protocol)

[5], which uses energy and communication cost for cluster head formation restricts the selection of two nodes within the same transmission coverage. It provides flexible CH selection and inter-CH connectivity. This protocol introduces an extra communication overhead or cost since each node should constantly communicate with its neighbours for specific number of rounds. Thus it is uncomfortable large –scale networks.

Another protocol named Distributed Energy Efficient Clustering (DEEC) [6] proposed by researchers selects CH based on the probability of ratio of residual energy to the average energy of the network. It computes the reference energy that each node expend based on which a value of network lifetime is estimated. It induces an overhead in the network topology and failed to calculate the average energy precisely. LEACH-C [7], enhancement from LEACH adopts a centralized approach by sending its id, position and energy value to the BS for CH selection.

PEGASIS [8] proposed by S.Lindsey suffers delay for forming a chain to transfer the data to BS. It requires a complete overview of network. This method constructs chain instead of clusters and selects a leader for that chain. Nodes will transfer the data through the chain to the leader and later leader will forward the aggregated data to BS. TEEN [9] proposed by A.Manjeshwar, et al; will reports data only when the sensed attribute reaches a particular threshold. Thus it can't be used for periodic report application. As a solution to this, they later implemented APTEEN [10] which can be used in proactive and reactive conditions.

The paper proposed by Jung et al. mention CCS [11] in which an integrated approach of PEGASIS and cluster-based method is formulated. Here the entire network is divided into various clusters and in each cluster a chain is formed by selecting a leader without considering the residual energy. It makes unbalanced distribution of nodes in each cluster. TL-LEACH introduced by Loscri et al. [12] suggests a two-level hierarchy where there is primary CH and secondary CH compete themselves. Here selection of CH is done without considering residual energy of nodes. A lot of message passing introduces communication overhead and affects network lifetime.

EECS proposed by Ye et al. [13] needs global knowledge about distance between BS and each CH for making the network more energy efficient. Here the nodes compete themselves to beat others and win as CH. For this, each node send its residual energy to their neighbours and choose the one with highest energy as CH. LEACH-M [14] proposed by D. S. Kim, et.al; introduces node mobility which results in large number of packet losses while moving CH before selecting a new CH for the next iteration.

Base-Station Controlled Dynamic Clustering Protocol (BCDCP), proposed by Muruganathan et al. [15], is not suitable for large distance communication since it uses single hop routing strategy with centralized approach. In [16], Wu et al; introduces a sleep/wake scheduling

protocol that preserves energy by keeping the radio transceivers to sleep periodically. But it suffers scheduling and synchronizing overhead.

To improve the efficiency of clustering and to mitigate the energy consumption problem we propose a new method to determine the centre of cluster for selecting a best CH. This approach uses combination of firefly algorithm and nearest neighbour method to effectively choosing the centroid of cluster. The attractiveness of fly is calculated and updated in each round. Also we are calculating the distance between each node by using Euclidean distance formula. Based on both theses parameters a best values is selected as cluster centre.

III. FIREFLY BASED NEAREST NEIGHBOUR CHAIN ALGORITHM

Sensor nodes which are battery operated are most often constrained in energy due to difficulty and inability to replace or recharging the nodes. Thus one of the most challenges in designing a protocol is energy consumption. A WSN network should be self-organized and distributed by which each sensor node can detect changes in the environment effectively. With respect to flat based and location based routing protocol, the cluster based routing protocols provides much longer network longevity. Here the entire network is divided into several numbers of clusters and one node from each cluster is selected as CH. CH collects data from each cluster, aggregates it and forwarded to the sink. The major role in clustering is to divide the entire network into groups and select suitable CH. Here we are suggesting a method to find the centre of cluster based on which a CH can be selected.

The proposed method uses combination of firefly algorithm with nearest neighbour approach to find the centroid of cluster. Each iteration attractiveness of fly and distance between nodes are calculated and updated. At last, we select most suitable value as centre of cluster based on which CH is selected.

Two main parameters are considered in this approach: attractiveness and distance. Attractiveness implies the similarity of nodes present in the network. Distance between nodes is calculated based on the Cartesian distance of the nodes using Euclidean formula. In this phase, we combined firefly algorithm with nearest neighbour chain algorithm to find the centre of cluster with most optimal neighbour nodes present in the topology.

The attractiveness of the firefly can be calculated as:

$$\beta(r) = \beta_0 e^{-\gamma r^2} \quad (1)$$

where β_0 is the attractiveness at $r = 0$ and γ is the light absorption coefficient.

The Cartesian distance between any two sensor nodes can be determined by:

$$D(x, y) = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2} \quad (2)$$

where x_i and y_i denotes the (x,y) coordinates of node i whereas x_j and y_j denotes the (x,y) coordinates of node j.

The movement of the firefly i, which is attracted to firefly j is estimated by:

$$X_i = x_i + \beta_0 e^{-\gamma r^2} (x_j - x_i) + \alpha(\text{rand} - 0.5) \quad (3)$$

Objective function which is used to find the centre of the clusters with the proposed FNNC algorithm can be formulated as follows

$$\text{Objective function} = \text{Dis}(X, Y) = \sqrt{\sum_{i=1}^d (X_{pi} - Y_{ji})^2} \quad (4)$$

where X_{pi} is the p^{th} data path vector and Y_{ji} is the distance vector of cluster j.

The aim is to find minimum value for objective function after the entire iteration completed. During each iteration, the movement and distance of the firefly gets updates.

Distance can be updated by using the formula:

$$D(x_{best}, y_{best}) = \sqrt{(x_i - x_{gbest})^2 + (y_i - y_{gbest})^2} \quad (5)$$

Updation of firefly movement can be expressed as:

$$X_{i+1} = x_i + \beta_0 e^{-\gamma r^2} (x_j - x_i) + \beta_0 e^{-\gamma r_{i,gbest}^2} (x_{gbest} - x_i) + \alpha(\text{rand} - 0.5) \quad (6)$$

The steps in the proposed clustering algorithm can be explained as follows:

Algorithm FNNC(K ,D)

//Let K and D be the random population and number of cluster centers respectively. The term 'T' denotes the iteration value. MAX denotes maximum number of iterations.

Initialize T=1

Initialize MAX=100

Initialize fireflies with K and D.

If (T < MAX)

Calculate $\text{Objective function} = \text{Dis}(X, Y) = \sqrt{\sum_{i=1}^d (X_{pi} - Y_{ji})^2}$

If(D[i][j] > D[i][i]) then

Move firefly i toward j based on

$$X_{i+1} = x_i + \beta_0 e^{-\gamma r^2} (x_j - x_i) + \beta_0 e^{-\gamma r_{i,gbest}^2} (x_{gbest} - x_i) + \alpha(\text{rand} - 0.5)$$

to update the locations

End if

T= T + 1

End if

Algorithm 1: Steps in FNNC Algorithm

From the above proposed algorithm, the following inference is made:

The most important parameter in firefly algorithm is γ (Absorption coefficient), it plays very crucial role in determining the speed of convergence and how FA algorithm behaves. Theoretically, $\gamma \in [0, \infty)$ but in actual practice, the value of γ is taken as 1. So for almost all the applications it varies from 0.01 to 10. Light intensity I_i of a firefly u_i at location x_i is determined by the objective function. For our proposed method, firefly and the location express in terms of node and location of the node in WSN respectively.

IV. CONCLUSION AND FUTURE WORKS

Cluster based routing protocol plays a major role in WSN communication. This type of network topology is easier to implement, manage and deploy. Data aggregation at each CH reduces redundancy and mitigates the communication overhead. The major concern is to select a node as CH for communication to the BS. This paper mainly focused on how to find out the centre of cluster for selecting a CH. Because an efficient selection CH makes the communication overhead lower and improve the network lifetime. The proposed method uses firefly algorithm with nearest neighbour chain method to calculate the centroid. It achieves the aim by considering two parameters: attractiveness and distance. At each iteration, attractiveness or firefly movement and distance of nodes get updated. We are comparing the global best value with current best and initialize cluster centre with global best value. This process continues until maximum iteration reached.

As future work, Genetic Algorithm based Harmony Search algorithm can be implemented for optimal CH selection. Here initially the entire nodes can be considered as population for which we are calculating fitness value. Then those which having highest fitness values are taken and crossover each other. By using this method best nodes can be selected as CH.

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