

# Classification-Segmentation Pipeline for MRI via Transfer Learning and Residual Networks

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**Abstract**—Artificial intelligence association into brain magnetic resonance imaging (MRI) and clinical practices embrace substantial cancer diagnosis improvement. The advancement of deep learning has improved the processing and analysis of MRI, boosting models' performance, decreasing the destructive effects of data sources overload, and increasing accurate detection and time efficacy. However, that specific dataset leads to diverse research fields such as image processing and analysis, detection, registration, segmentation, and classification. This paper proposes a decision-making pipeline for MRI data by combining image classification and segmentation. First, the pipeline should correctly produce a correct decision given an MRI image. If the figure is classified as defective, the pipeline can extract defect regions and highlight them accordingly. We have implemented several advanced convolutional neural networks with transfer learning and residual techniques to address two broad clinical concerns in one decision-making workflow.

## I. INTRODUCTION AND MOTIVATION

TODAY, clinical practice is an area of interest and research where extensive research and technical recommendations have been developed in response to increasingly complex challenges [1], [2], [3]. Identifying and analyzing diseases is increasingly difficult because they are ever more sophisticated. Fortunately, artificial intelligence has revolutionized clinical practice in many areas such as cancer diagnosis with medical imaging [4], automatic classification diseases based on descriptions [5], [6], and maximizing hospital efficiency [7]. Among many approaches, deep learning has been proven superior in a wide range of clinical data and practice scenarios. Regarding MRI, the complex feature can be represented effectively by utilizing deep learning-based models in detection, registration, classification, and segmentation problems.

Employing a convolutional neural network (CNN) for image classification is one of the reasonable rises, and it is an essential model in developing an automatic disease diagnosis [8], [9]. Among competitors of the ImageNet challenge in 2012, the deep learning-based model AlexNet proposed by Krizhevsky et al.[10] won the championship. CNN has become the backbone architecture for addressing almost all problems in computer science. Many CNN-based approaches have been investigated for addressing MRI image classification [11].

Due to CNN's dominant performance in the MRI classification domain, people began exploiting CNN for MRI segmentation. More specifically, MRI diagnosis is the subdivision of different brain regions to detect brain diseases, such as

cancer and Parkinson's syndrome. Consequently, automatic segmentation of defect regions in MRI is significantly essential in everyday clinical routines and medical research [12]. With the performance of CNN, excellent segmentation approaches have been developed based on CNN and continuously become front tier in particular segmentation competitions [13].

However, one interesting research question that someone might consider is that we should combine several research domains and develop a practical workflow that supports medical analysis and recommendation. This article aims to propose a decision-making pipeline for MRI data by combining image classification and image segmentation. First, given an MRI image, the classification part of the pipeline should make a correct decision. If the brain MRI is classified as defective, the segmentation part can extract defect regions and highlight them accordingly. Thus, the Class-Seg workflow is designed and implemented by leveraging transfer learning, residual network [14] design, and several state-of-the-art CNN models.

## II. BLUEPRINT OF THE MRI CLASS-SEG PIPELINE

As mentioned in the previous section, we propose a machine learning pipeline to support MRI diagnosis by (i) applying transfer learning techniques to select the best detection model and (ii) integrating classification with segmentation in one channel to improve MRI diagnosis and treatment. The blueprint of our proposed pipeline is presented in Figure 1. Here, the MRI dataset is randomly divided without replacement into several portions. Five primarily used CNN models are selected for the task of classification. Technically, the CNN part's weights are transferred from pre-trained models on ImageNet. The CNN part is freezing out of the back-propagation process. Then it is flattened and fed into our proposed dense layers, see Figure 2, where the weights are learned. The authors implement ResUNet based on UNet architecture comprising several residual blocks to overcome the vanishing gradients problems in deep CNN architecture regarding the segmentation task. We present how classification and segmentation tasks can be combined in Algorithm 1. Note in the pseudo-code that phases 1 and 2 correspond to points (i) and (ii) in this section, respectively. Transfer learning is applied in phase 1, where multiple models are reused, while in phase 2, we train the segmentation model from scratch.

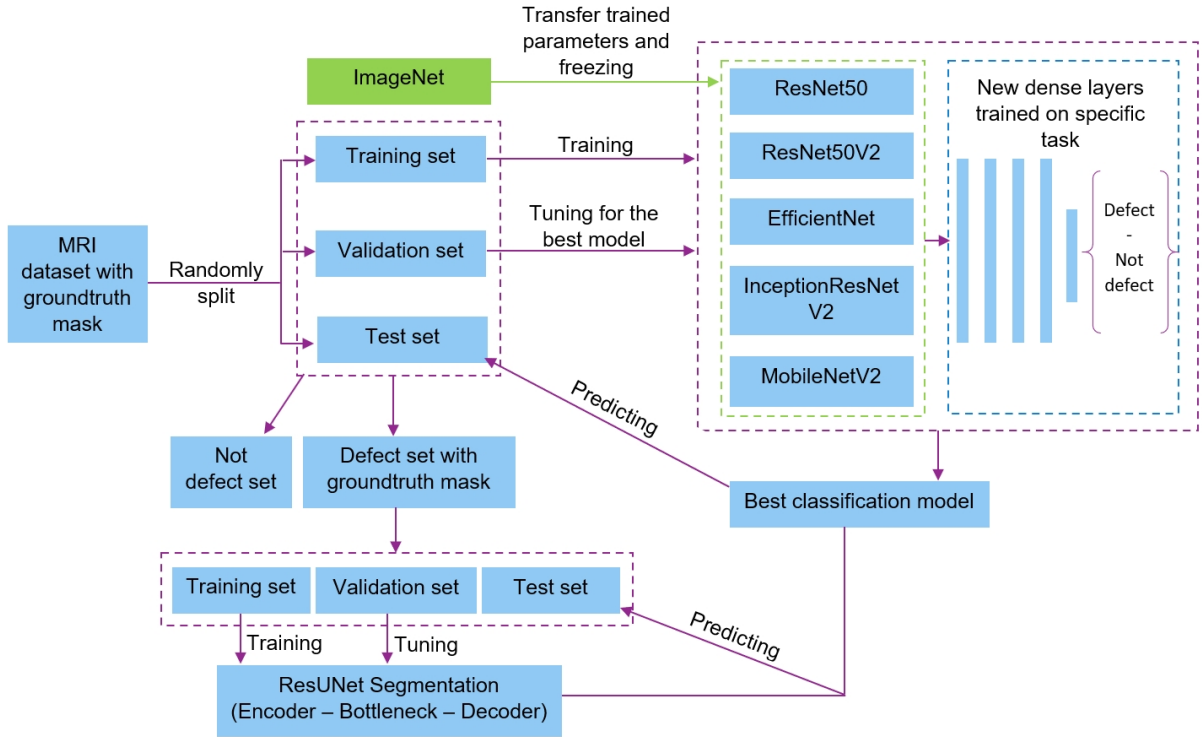


Figure 1. The Proposed Classification-Segmentation Pipeline for Brain MRI.

Layer (type)	Output Shape	Param #
dense (Dense)	(None, 1024)	(from flatten)
dropout (Dropout)	(None, 1024)	0
dense (Dense)	(None, 1024)	1049600
dropout (Dropout)	(None, 1024)	0
dense (Dense)	(None, 1024)	1049600
dropout (Dropout)	(None, 1024)	0
dense (Dense)	(None, 256)	262400
dropout (Dropout)	(None, 256)	0
dense (Dense)	(None, 2)	514

Figure 2. Our proposed dense layers to be trained with MRI dataset.

### III. TRANSFER LEARNING

Transfer learning technique is to reuse the pre-trained models learned in one or more different domains and utilize the knowledge to enhance learning in any other domain [15], [16]. Reusing a trained model that solves a problem similar to your data source is very versatile. It allows a machine learning approach to be applied to data drawn from a wide range of different sources from the one upon which it has initially been trained [17], [18], [19]. It might take weeks to train modern CNN models with millions of parameters fully. Transfer learning proposed many re-trained options such as fine-tuning model weight, freezing layers, and even re-train from scratch. It shortcuts a lot of network design and training

by transferring a trained set of parameters from a predefined category and re-weights the model's parameters from new data. This technique, called inductive transfer learning, aims to effectively improve training in the target domain by practicing knowledge transferability from many other sources. By re-updating weights, the effects of dissimilar observations will be reduced, and it might thus produce a more objective approach. Every CNN-based model consists of two parts, a series of convolutional-pooling layers as the tail and sequences of dense layers as the head. One transferability strategy is to transfer the learned parameters to the tail and freeze it. Flatten is applied at the tail's last layer before integrating it into the head. Backpropagation and parameters update is done within the head. In Figure 3, we present the key difference between traditional machine learning and the adoption of transfer learning.

### IV. EXPERIMENTS

#### A. Experimental MRI Dataset

We have exploited our proposed classification-segmentation pipeline on the most reputable brain MRI segmentation dataset<sup>1</sup>. By the time we conducted this paper, there had been 42 code solutions and six discussions on the dataset. However, none developed a systematic pipeline for the dual task of binary classification and image segmentation. The 1GB contains 7860 brain MRI figures manually annotated with fluid-attenuated inversion recovery (FLAIR) abnormality

<sup>1</sup><https://www.kaggle.com/mateuszbeda/lgg-mri-segmentation>

**Algorithm 1** The proposed classification-segmentation pipeline.

- 1: **Phase 1:** Train classification model
- 2: Splitting MRI dataset into 70%-15%-15% training, validation (val.), test sets
- 3: **for** each model to apply transfer learning **do**
- 4:   Transfer pretrained weights from ImageNet to the CNN part and freeze it
- 5:   Integrate the proposed dense layers, see Figure 2
- 6:   Optimize Equation 2
- 7: **end for**
- 8: Get the best classification model, called *model 1*
- 9:
- 10: **Phase 2:** Train segmentation model
- 11: Defect MRI images are split into 70%-15%-15% training, val., test(\*) sets
- 12: Optimize Equation 3
- 13: Get the optimal segmentation model, called *model 2*
- 14:
- 15: **Phase 3:** Class-Seg combination
- 16: **for** Each image  $i$  in test(\*) **do**
- 17:   **if** *model 1* predicts  $i$  as non-defect **then**
- 18:     Continue
- 19:   **else**
- 20:     *model 2* segments the defect region
- 21:   **end if**
- 22: **end for**

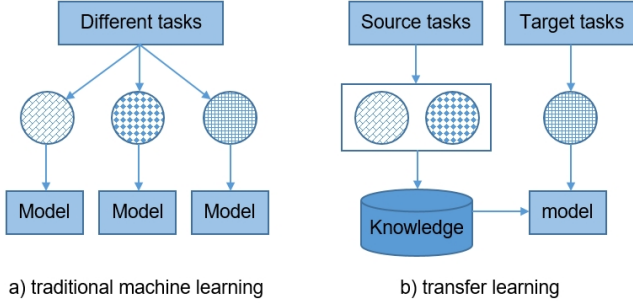


Figure 3. In a), different models for separated tasks. In b) one approach can be re-used for many tasks.

segmentation masks. First, the dataset was collected from 110 patients included in The Cancer Genome Atlas lower-grade glioma collection. Then, the images with at least one possible FLAIR sequence and genomic cluster are selected.

### B. Loss Functions

In the previous section, the authors have mentioned that the pipeline consists of two distinct tasks: first, the model should correctly classify defective images from normal ones; second, after the image is classified as defected, it is fed into segmentation to reveal the region of abnormality. Hence, the pipeline applies two different loss functions: categorical cross-entropy loss to address binary classification scenario and Focal

Tversky [20] loss which is highly recommended for handling imbalanced data and small regions-of-interest segmentation.

Categorical cross-entropy (CCE) loss is a softmax activation plus a cross-entropy (CE) loss. The CE is defined as follows in a binary classification problem.

$$CE = \sum_{i=1}^{C=2} y_i \log(s_i) = -y_1 \log(s_1) - (1-y_1) \log(1-s_1), \quad (1)$$

where  $y_i$ ,  $s_i$ , and  $C$  are the groundtruth, the predicted CNN score and the number of class respectively. Then CE plus softmax activation which yields CCE as follows.

$$CCE = - \sum_i^C y_i \log(f(s)_i), \quad (2)$$

where  $f(s)_i = \frac{e^{s_i}}{\sum_j^C e^{s_j}}$ .

The focal Tversky (FT) loss is defined as follows.

$$FT = \sum_i^C (1 - T_i)^{\frac{1}{\gamma}}, \quad (3)$$

where  $\gamma = \frac{4}{3}$  by default as described in [20].  $T_i$  is denoted as follows.

$$T_i = \frac{\sum_{j=1}^N p_{ji} g_{ji} + \epsilon}{\sum_{j=1}^N p_{ji} g_{ji} + \alpha \sum_{j=1}^N p_{j\bar{i}} g_{ji} + \beta \sum_{j=1}^N p_{ji} g_{j\bar{i}} + \epsilon}, \quad (4)$$

where  $N$  provides the total number of pixels in an image.  $\epsilon$  is numerical stability.  $p_{ji}$  is the probability that pixel  $j$  is of the lesion class  $i$ , while  $p_{j\bar{i}}$  is that of non-lesion class  $i$ . The same meaning is applied to  $g_{ji}$  and  $g_{j\bar{i}}$ .  $\alpha$  and  $\beta$  are tunable hyperparameters to shift the recall emphasis in case of large class imbalance. In our experiments, we set the value of  $\alpha = 0.7$  and  $\beta = 0.75$ .

### C. Experimental Results

For the task of classification, the authors have deployed 5 well-known CNN models in computer vision community, e.g. ResNet50 [21], ResNet50V2 [21], InceptionResNetV2 [22], EfficientNet [23], and MobileNetV2 [24]. These models are easily called using TensorFlow API [25]. While in the segmentation task, the authors implement ResUNet [26], one of the most state-of-the-art segmentation models. The authors run three times for each approach and report the average scores. The classification and segmentation performance of all models have presented in Table I. We illustrate several segmentation samples in Figure 4.

In Table I, the first five models are used to select the best candidate for the classification task. The best solution is the InceptionResNetV2 model, which achieves 95% of accuracy. The authors report the number of trainable parameters, the average training duration, the accuracy score on the test set, and two basic F1-score schemes [27]. Turning to segmentation,

Table I  
CLASSIFICATION AND SEGMENTATION PERFORMANCE OF ALL MODELS.

Model	Trainable params (million)	Training time (minutes)	Test Acc.	Micro avg F1-score	Macro avg F1-score
ResNet50	59.452.162	15.04	0.93	0.93	0.92
ResNet50V2	59.436.930	13.36	0.88	0.88	0.86
InceptionResNetV2	70.795.106	27.78	<b>0.95</b>	<b>0.95</b>	<b>0.95</b>
EfficientNetB0	27.342.206	13.48	0.66	0.67	0.43
MobileNetV2	25.558.530	09.33	0.41	0.42	0.37
			Val. Tversky		
ResUNet	1.206.129	0.63	0.89	-	-

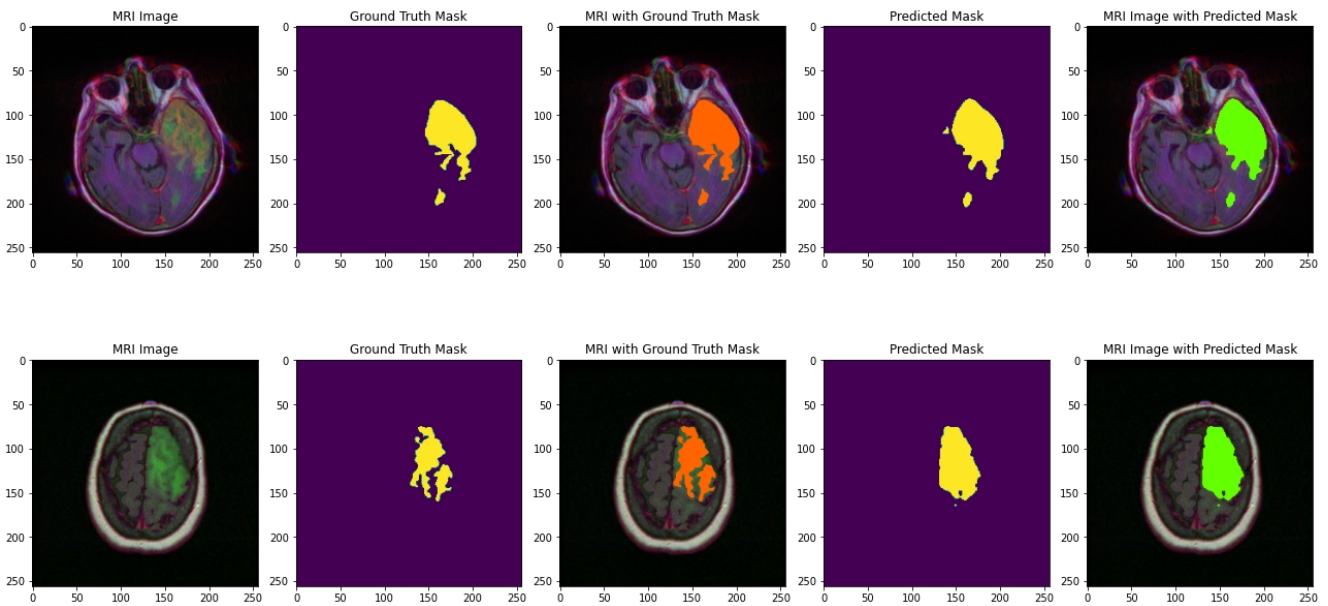


Figure 4. The Result of the Segmentation Process. From left to right in each row, the original MRI figure, annotated groundtruth mask on defect region, the overlapping of them, the predicted mask provided by the segmentation process, and the predicted overlapping.

the authors implement ResUNet because of the speed, high performance. We report the Tversky score for this task.

#### D. Reproducibility

The authors have conducted all experiments on Google Colab. GPU runtime type has been activated by default. We encourage further reproducibility by engaging readers by revealing all models' weights and architecture. Regarding the paper's length restriction, the authors add additional materials and other experiment resources in our GitHub repository<sup>2</sup>.

#### V. CONCLUSION

We have described and implemented the proposed Class-Seg workflow by leveraging transfer learning and residual network together with several state-of-the-art convolutional neural models. We aim to combine the classification and segmentation of brain MRI into a single clinical practice. To our knowledge, we are the first to combine two research

directions on the well-known Kaggle brain MRI dataset, in which more than 40 code solutions have been investigated. Intensive experiments have been conducted to develop a clinically acceptable automatic workflow for better brain MRI diagnosis.

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<sup>2</sup><https://github.com/duongtrung/Class-Seg-Brain-MRI>

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