

# **Correctness issues of UML Class and State Machine Models in the C# Code Generation and Execution Framework**

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Abstract — Model driven approach for program development can assist in quick generation of complex and highly reliable applications. Framework for eXecutable UML (FXU) transforms UML models into C# source code and supports execution of the application reflecting the behavioral model. The framework consists of two parts code generator and run time library. The generated and executed code corresponds to structural model specified in class diagrams and behavioral model described by state machines of these classes. All single concepts of state machines included in the UML 2.0 specification (and further) are taken into account, including all kinds of events, states, pseudostates, submachines etc. The paper discusses the correctness issues of classes and state machine models that have to be decided in the framework in order to run a model-related and high quality C# application. The solution was tested on set of UML models.

# I. INTRODUCTION

MODEL Driven Engineering (MDE) represents software development approaches in which creation and manipulation of models should result in building of an executable system [1].

Industrial product development puts a lot of attention on fast implementation of the needed functionalities. Modeldriven approach to program development offers a promising solution to these problems. The complex behavioral models can be designed and verified at the early stages of the whole product creation cycle and automatically transformed into the code preserving the desired behavior.

State machines, also in the form of statecharts incorporated in the UML notation [2], are a widely used concept for specification of concurrent reactive systems. Proposal for execution of behavioral UML models suffers from the problem that no generally accepted formal semantics of UML models is available. Therefore, validation of UML transformation and model behavior depicted in the resulting code is difficult. Rather than completely formalizing UML models, we try to deal with selected aspects of the models.

Checking of models is important in Model Driven Architecture (MDA) approaches [3], [4] where new diagrams and code are automatically synthesized from the initial UML

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model: all the constructed artifacts would inherit the initial inconsistency [5].

Inconsistency and incompleteness allowed by UML can be a source of problems in software development. A basic type of design faults is concerned with the well-formedness of diagrams [2]. Typically, completeness of a design requires that introduced model elements are specified with their features and usage of one element can imply a usage of another, directly related model element. In the current modeling CASE tools some completeness conditions can be assured automatically (e.g., default names of roles in associations, attributes, operations etc.). Incompleteness of models can be to be strongly related to their inconsistency, because it is often impossible to conclude whether diagrams are inconsistent or incomplete [6]. Therefore, within this paper we will refer to model defects as to correctness issues.

The Framework for eXecutable UML (FXU) offers a foundation for applying MDA ideas in automation of software design and verification. The FXU framework was the first solution that supported generation and execution of all elements of state machine UML 2.0 using C# language [7]. In order to build an application reflecting the modeled classes and their behaviors specified by state machines, we resolved necessary semantic variation points [8]. Semantic variation points are aspects that were intentionally not determined in the specification [2] and its interpretation is left for a user.

It was also necessary to provide some correctness checking of a model. This paper is devoted to these issues. To present potential problems we selected one target application environment, i.e., creation of application in C# language. The verification of an input UML model is based on a set of hard coded rules. Some of the rules are general and can be applied for any object-oriented language, as they originate directly from the UML specification [2]. Other rules are more environmental specific because they take also into account the features of the target language - C#. The verification is performed during transformation of class and state machine models into the corresponding code; it is so-called static verification. Other set of rules is used during execution of the code corresponding to given state machines; so-called dynamic verification. For all correctness rules the appropriate reaction on the detected flaws were specified.

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ments performed and the conclusions finish the paper.

## II. RELATED WORK

A huge amount of research efforts is devoted to formalization of UML models, specification of their semantics and verification methods [9]-[13]. However they are usually not resolving the practical problems which are faced while building an executable code, because of many variation semantic points of the UML specification.

An attempt for incorporation of different variation points into one solution is presented in [14]. The authors intend to build models that specify different variants and combine them with the statechart metamodel. Different policies should be implemented for these variants.

Our work relates also to the field of consistency of UML models. The consistency problems in UML designs were extensively studied in many papers. It could be mentioned workshops co-located to the Models (former UML) series of conferences, and other works [5], [6], [15]-[17].

An interesting investigation about defects in industrial projects can be found in [18]. However the study takes into account only class diagrams, sequence diagrams and use case diagrams, mostly the relations among elements from different diagram types. The state machines were not considered.

Solutions to consistency problems in class diagrams were presented in [19]. The problem refers to constrains specifying generalization sets in class diagram, which is still not commonly used in most of UML designs.

Current UML case tools allow constructing incorrect models. They provide partial checking of selected model features, but it is not sufficient if we would like to create automatically a reliable application. More comprehensive checking can be found in the tools aimed at model analysis. For example, the OO design measurement tool SDMetrics [20] gives the rules according to which the models are checked. We used the experiences of the tool (Sec. IV), but it does not deal with state machine execution nor with C# language.

Many modeling tools have a facility of transforming the models into code in different programming languages. However, the most of them consider only class models. We compared functionality of twelve tools that could also generate code from state machines. Only few of them took into account more complex features of state machines, like choice pseudostates, deep and shallow history pseudostates, deferred events or internal transitions. The most complete support for state machines UML 2.0 is implemented in the Rhapsody tool [21] of IBM Telelogic (formerly I-Logix). However it does not consider C# language.

Different approaches to generation of the code from behavioral UML models can be used. The semantics of a state machine can be directly implemented in the generated code [22]. Another solution is usage of a kind of a run-time environment, for example a run-time library as applied in the FXU framework. The consistency problems remain also using tools for building executable UML models [23], [24]. Different subsets of UML being used and we cannot assure that two interchanged models will behave in the same way. Specification of a common subset of UML specialized for execution is still an open idea.

#### III. CODE GENERATION AND EXECUTION IN FXU

Transformation of UML models into executable application can be realized in the following steps.

1.A model, created using a CASE modeling tool, is exported and saved as an XML Metadata Interchange (XMI) file.

2. The model (or its parts) is transformed by a generator that creates a corresponding code in the target programming language.

3. The generated code is modified (if necessary), compiled and linked against a Runtime Library. The Runtime Library contains realization of different UML meta-model elements, especially referring to behavioral UML models.

4. The final application, reflecting the model behavior, can be executed.

It should be noted, that steps 1) and 2) can be merged, if the considered code generator is associated with the modelling tool.

The process presented above is realized in the FXU framework [7]. The target implementation language is C#. The part of UML model taken into account comprises classes and state machines. The input models are accepted in UML2 format, an XMI variant supported by Eclipse. Therefore it is not directly associated with any modelling tool. However, all experiments mentioned in Sec. V were performed with UML models created using IBM Rational Software Architect [25].

The FXU framework consists of two components - FXU Generator and FXU Runtime Library. The Generator is responsible for realization of step 2. The FXU Runtime Library includes over forty classes that correspond to different elements of UML state machines. It implements the general rules of state machine behavior, independent of a considered model, e.g., processing of events, execution of transitions, entering and exiting states, realization of different pseudostates. It is also responsible for the runtime verification of certain features of an executed model.

Transforming class models into C# code, all model elements are implemented by appropriate C# elements. The template of a resulting programming class can be found in [7]. Principles of code generation from the class models are similar to other object-oriented languages and analogues to solutions used in other tools.

A distinctive feature of FXU is dealing with all UML state machine elements and their realization in C# application. Therefore we present selected concepts of state machines with their implementation in C#. We point out different C# specific mechanisms used in the generated application. Using selected solutions we would like to obtain an efficient and reliable application.

State machines can be used at different levels of abstraction. They can model behavior of an interface, a component, an operation. Protocol state machines are intended to model protocols. The primary application of behavioral state machine in an object-oriented model is description of a class. A class can have attributes keeping information about a current state of an object. Classes have operations that can trigger transitions, send and receive events. Therefore, we assumed that the code will be generated and further executed only for behavioral state machines that are defined for certain classes that are present in the structural model.

An exemplary UML model is shown in Fig. 1. A given class has an attribute, four operations and its behavior specified by a state machine. The state machine consists of simple state S1 and complex state S2 including two orthogonal regions. In guard conditions and triggers the operations and attribute of the class are used. Extracts of the C# code corresponding to the example and created by the FXU generator are given in the Appendix.

For any state machine of a class, a new attribute of *StateMachine* type is created. Each class having a state machine has also two additional methods *InitFXU* and *StartFXU*. Method *InitFXU* is responsible for creation and initialization of all objects corresponding to all elements of state machine(s) associated with the class, such as regions, states, pseudostates, transitions, activities, events, triggers, guards, actions, etc. Method *StartFXU* is used for launching a behavior of state machine(s).

Any state can have up to three types of internal activities *do, entry, exit.* The activities of a state are realized using a delegate mechanism of C#. Three methods *DoBody, Entry-Body* and *ExitBody* with empty bodies are created for any state by default. If an activity exists a corresponding method with its body is created, using information taken from the model. Applying delegate mechanism allows defining the methods for states without using of inheritance or overloaded methods. Therefore the generated code can be simple, and generation of a class for any single state can be avoided. A state machine is not generated as a state design pattern [26], because we would like to prevent an explosion of number of classes.

Three transition kinds can be specified for a transition, *external*, *internal* and *local* transitions. Triggering an internal

transition implies no change of a state, exit and entry activities are not invoked. If an external transition is triggered it will exit its source state (a composite one), i.e. its exit activity will be executed. A local transition is a transition within a composite state. No exit for the composite (source) state will be invoked, but the appropriate exits and entries of the substates included in the state will be executed.

A kind of a transition can be specified in a model, but in praxis this information is rarely updated and often inaccurate. Therefore we assumed that in case of composite states a kind of generated transition is determined using a following heuristics:

- If the target state is different than the source state of a transition and the source state is a composite state, the transition is external.
- Else, the transition is defined in a model as internal it is treated as an internal transition.
- Otherwise, the transition is local.

A transition can have its guard condition and actions. They are created similarly to activities in states, using delegate mechanism of C#. If a body of an appropriate guard condition or action is nonempty in a model, it is put in the generated code. It should be noted that verification of logical conditions written in C# is postponed to the compilation time.

States, pseudostates, transitions and events are created as local variables. Signals are treated in different way. They are created as classes, because they can be generalized and specialized building a signals hierarchy. If a certain signal can trigger an event also all signals that are its descendants in the signal hierarchy can trigger the same event. This feature of signals was implemented using the reflection mechanism of C# [27].

Events should have some identifiers in order to be managed. Change events and call events are identified by unique natural numbers assigned to the events. A time event is identified by a transition which can be triggered by this event. A completion event is identified by a state in which the event was generated. Finally, for a signal event the class of the signal, i.e., its type, is used as its identifier.

There are some elements of a UML model that include a description in a form not precisely specified in the standard, but dependent on a selected notation, usually a programming



Fig. 1 Example - a class and its state machine

language. There are, for example, guard conditions, implementation of actions in transitions or in states, body of operations in classes. They can be written directly in a target implementation language (e.g., C#). During code generation these fragments are inserted into the final code. Verification of the syntax and semantics of such code extracts is performed during the code compilation and execution according to a selected programming language.

Interpreting different concepts of state machines we can use parallel execution. In the FXU RunTime Library it is implemented by multithreading. Multithreading is used for processing of many state machines which are active in the same time, e.g., state machines of different classes. It is used also for handling submachine states and orthogonal regions working within states, and for other processing of events. In the Appendix, parts of an output trace generated during execution of the exemplary state machine (Fig. 1) are shown. We can observe different threads, identified by number in brackets, that were created to deal with encountering events. For example, realization of transition from the pseudostate fork to substate S3 in S2 launched thread "[11]". Thread "[12]" was created to implement transition from the fork pseudostate to substate S1 inS2. In other execution run of the application the numbers and ordering of threads can be different

Event processing during state machine execution is performed according to the rules given in UML specification [2]. Basic algorithms of FXU realization, like execution of a state machine, entry to a state, exit from a state, were presented in [7]. For every state a queue was implemented that pools incoming events. Events can be broadcasted or sent directly to the selected state machines. Events trigger transitions that have an active source state and their guard conditions evaluate to true. If many transitions can be fired, transition priorities are used for their selection. We had proposed and implemented an extended definition of transitions priority, in order to resolve all conflicts in case many transitions can be fired. This could not be achieved based only on the priority definition given in [2]. The detailed algorithm of selecting non-conflicting transitions can be found in [8]. Also resolving of other variation points, especially dealing with entering and exiting orthogonal states, is shown in [8].

## IV. VERIFICATION OF MODEL CORRECTNESS

While generating valid C# code from UML class and state machine diagrams the certain conditions should be satisfied. There are many possible shortcomings present in the models that are not excluded by the modeling tools, or should be not prohibited due to possible model incompleteness at different evolution stages. They were analyzed taking into account the practical weaknesses of model developers.

The prepared correctness rules were based on three main sources: the specification of UML [2], the rules discussed in related works and other comparable tools, in particular in [20], and finally the own study, especially taking into account the features of C# language - the target of the model transformation [27].

Various shortcomings can be detected during different steps of application realization (Sec. 3). Many of them can be identified directly in the model, and therefore detected during model to code transformation step (step 2). Verification of such problems will be called static, as it corresponds to an automated inspection of a model. Other flaws are detected only during execution of the resulting application (step 4). Such dynamic verification will be completed by the appropriate classes of the FXU Runtime Library.

In tables I-III defects identified in classes and state machines are presented. The last column shows severity associated to the shortcomings. Three classes of severity are distinguished. If a defect detected in a model is called as *critical* the model is treated as invalid and the code generation is interrupted without producing the output. Later cases are clas-

No	Detected defects	Reaction	Severity
1	A generalization of an interface from a class was detected	Stop code generation	critical
2	A name of an element to be generated (e.g. a class, an interface, an operation, an attribute) is a keyword of C# language	Stop code generation	critical
3	A class relates via generalization to more than one general class	Stop code generation	critical
4	A cycle in class generalization was detected	Stop code generation	critical
5	A name of an element to be generated is missing	Generate the element pattern without its name. The element name has to be supplemented in the generated code.	medium
6	A name of an element to be generated is not a valid C# name. It is assumed that white characters are so common shortcoming that they should be automatically substituted by an underline character.	As above	medium
7	An interface visibility is private or protected.	Use <i>package</i> visibility .	low
8	A class visibility is private or protected .	Use package visibility.	low
9	An interface is abstract.	Treat the interface as no abstract.	low
10	An interface has some attributes.	Ignore attributes of the interface.	low
11	An interface has nested classes	Ignore classes nested in the interface.	low
12	A class that is no <i>abstract</i> has abstract operations.	Treat the class as <i>abstract</i> .	low

TABLE I. DEFECTS DETECTED IN UML CLASS DIAGRAMS (STATIC)

No	Detected defects	Reaction	Severity
1	A cycle in signal generalization was detected	Stop code generation	critical
2	A signal inherits after an element that is not another signal	Stop code generation	critical
3	A signal relates via generalization to more than one general signal	Stop code generation	critical
4	A region has more than one initial pseudostate	Stop code generation	critical
5	A state has more than one deep history pseudostate or shallow history pseudostate	Stop code generation	critical
6	There are transitions from pseudostates to the same pseudostates (different than a choice pseudostate)	Stop code generation	critical
7	There are improper transitions between orthogonal regions	Stop code generation	critical
8	A transition trigger refers to an nonexistent signal	Stop code generation	critical
9	An entry point, join or initial pseudostate has no incoming transition or more than one incoming transition	Stop code generation	critical
10	A deep or shallow history pseudostate has more than one outgoing transition	Stop code generation	critical
11	A transition from an entry/exit point to an entry/exit point	Stop code generation	critical
12	An exit point has no any incoming transition	Stop code generation	critical
13	Transitions outgoing a fork pseudostate do not target states in different regions of an orthogonal states	Stop code generation	critical
14	Transitions incoming to a join pseudostate do not originate in different regions of an orthogonal state	Stop code generation	critical
15	There is a transition originating in an initial pseudostate or a deep/shallow history pseudostate and outgoing a nested orthogonal state	Stop code generation	critical
16	The region at the topmost level (region of a state machine) has no initial pseudostate	Warn a user	medium
17	A transition outgoing a pseudostate has a trigger	Ignore the trigger	medium
18	A tgransition outgoing a pseudostate (different from a choice or junction vertex) has a nonempty guard condition	Ignore the guard condition	medium
19	A transition targeting a join pseudostate has a trigger or nonempty guard condition	Ignore the trigger and/or condition	medium
20	A trigger refers to a non-existing operation	The transition will be generated but it cannot be triggered by this event	medium
21	A trigger refer to an abstract operation or to an operation of an interface	as above	medium
22	A time event is deferred	Treat the event as not being deferred	medium
23	A final state has an outgoing transition	Warn a user	medium
24	A terminate pseudostate has an outgoing transition	Warn a user	low

TABLE II. DEFECTS DETECTED IN UML STATE MACHINES (STATIC)

sified as *medium* and *low*. In both cases the code generation is proceeded, although for *medium* severity it can require corrections before compilation. In all cases information about all detected shortcomings is delivered to a user. A detailed reaction to the found defect is described in the third column. While assigning severity levels and reactions to given defects we took into account general model correctness features but also requirements specific for C# applications.

# A. Verification of Class Models

Class diagrams describe a static structure of a system, therefore many their features can be verified statically before code generation. Table I summaries defects that are checked during static analysis of UML class models. It was assumed that some improvements can be added more conveniently in the generated code than in a model. The class models can be incomplete to some extend and we can still generate the code. Admission of certain model incompleteness can be practically justifiable because of model evolution. It should be noted that not all requirements of generated code are checked by the generator. Some elements are verified later by the compiler. It concerns especially elements that are not directly defined by the UML specification, like the bodies of operations.

# **B.Verification of State Machines**

Similarly to class diagrams, different defects of state machines can be detected statically in the models. They are listed in Tab. II. Static detection of shortcomings in state machines is realized twice. First, it is made before model to source transformation (step 2). Second correctness checking is fulfilled before state machine execution. It is a part of step 4, during the initialization of the structure of a state machine.

For example, a static verification can be illustrated using a state machine from Fig. 1. Transition outgoing state S3\_inS2 has an event trigger - calling of an operation finish\_operA(). However, this transition targets the join pseudostate. Therefore neither a trigger nor a guard condition can be associated with the transition. It violates the correctness rule 18 (Tab. II). This model flaw is quite often and is not critical. The

TABLE III. DEFECTS DETECTED IN UML STATE MACHINES (DYNAMIC)

No	Detected defects	Reaction	Severity
1	There is no enabled and no "else" transition outgoing a choice or junction pseudostate	Suspend execution - terminate	critical
2	A deep or shallow history pseudostate was entered that has no outgoing transitions and is "empty", i.e. either a final state was a last active substate or the state was not visited before	Suspend execution - terminate	critical
3	More than one transition outgoing a choice or junction pseudostate is enabled	Select one enabled transition and ignore the others	medium
4	There is no enabled transition outgoing a choice or junction pseudostate and there is one or more "else" transition outgoing this pseudostate	Select onr "else" transition and ignore other transitions	medium
5	More than one transition outgoing the same state is enabled	Select one transition and ignore the others	medium

trigger will be omitted in the generated code and the designer will be warned about this exclusion.

State machines model system behavior; therefore not all their elements can be statically verified. A part of defects is detected dynamically, i.e., during execution of state machines. For example, a situation that two enabled transitions are outgoing the same choice pseudostate can be detected after evaluation of appropriate guard conditions, namely during program execution. Defects detected dynamically in state machines are presented in Tab. III.

#### V. EXPERIMENTS

The presented approach for building the C# code and executing the automatically created applications was tested on over fifty models. The first group of ten models was aimed at classes. In experiments the correct and incorrect constructions encountering in class diagrams were checked, concerning especially association and generalization. Moreover, two bigger projects were tested. The first one was a part of MDA project called Acceleo [28]. The model described a design of a web page. The second one presented a metamodel of an object-oriented modeling language [29].

Models from the next group (above forty models) comprised different diagrams, including both classes and state machines. All possible constructs of UML 2.x state machines were used in different situations in the models. The biggest design included five state machines with about 80 states and 110 transitions, using complex and orthogonal states, different kinds of pseudostates and submachine states.

The programs realizing state machines were run taking into account different sequences of triggering events. The behavior modeled by state machines was observed and verified using detailed traces generated during program runs. They helped to test whether the obtained program behavior conforms to desired state machine semantics. For complex models, filtered traces that included selected information were also used.

The performed experiments have showed that an application realizing a behavior specified in state machine models can be developed in an effective and reliable way.

# CONCLUSION

In this paper we discussed the problems of creation of valid C# applications realizing ideas modeled by classes and

their state machines. Different C# mechanisms were effectively used for implementation of the full state machine model defined in the UML 2.x specification. We showed which correctness issues of models have to be checked during model transformation (static verification) and during application execution (dynamic verification). The detailed correctness rules help a developer to cope with possible flaws present in UML models. In the difference to other tools, using FXU the state machines including any complex features can be effectively transformed into corresponding C# application. The tool support speeds up building of reliable applications including complex behavioral specifications. It can be especially useful for developing programs in which nontrivial state machines are intensely used, e.g., dependable systems, embedded reactive systems.

#### Appendix

The appendix includes extracts of C# code generated for an exemplary class and its state machine shown in Fig. 1. Code of class operations are omitted (line 3). Method *Init-*Fxu() creates appropriate structure of the state machine. Method *StartFxu()* initializes behavior of the state machine.

```
public class A class
1
                          {
2
    private int x attrA;
3
    // operations of A_class (omitted)
    StateMachine sml = new
4
     StateMachine("OwnedStateMachine1");
5
  public void InitFxu() {
6
    Region r1 = new Region("Region1");
    sml.AddRegion(r1);
7
    InitialPseudostate v2 = new
8
               InitialPseudostate("");
9
    r1.AddVertex(v2);
10
    FinalState v3 = new FinalState("");
11
    r1.AddVertex(v3);
    State v4 = new State("S1");
12
13
    v4.EntryBody = delegate() { init x();
                                            };
    r1.AddVertex(v4);
14
    State v5 = new State("S2");
15
16
    v5.DoBody = delegate() { work operA(); };
    r1.AddVertex(v5);
17
18
    Region r2 = new Region("Region1");
19
    v5.AddRegion(r2);
20
    Region r3 = new Region("Region2");
21
    v5.AddRegion(r3);
    State v6 = new State("S2 inS2");
2.2
    v6.EntryBody = delegate()
23
    {System.Threading.Thread.Sleep(10000); };
```

```
{System.infeading.infead.sieep(10000); };
24 r2.AddVertex(v6);
```

```
25
    State v7 = new State("S1 inS2");
26
    r2.AddVertex(v7);
27
    State v8 = new State("S3 inS2");
28
    r3.AddVertex(v8);
    Fork v9 = new Fork("");
29
    r1.AddVertex(v9);
30
31
    FinalState v10 = new FinalState("");
32
    r1.AddVertex(v10);
33
    Join v11 = new Join("");
34
    r1.AddVertex(v11);
35
    Transition t1 = new Transition(v2, v4);
36
    Transition t2 = new Transition(v4, v9);
37
    t2.GuardBody = delegate(){return x_attrA>=0;};
    Transition t3 = new Transition(v4, v10);
38
39
    t3.GuardBody = delegate(){return x_attrA<0;};</pre>
    Transition t4 = new Transition(v6, v11);
40
    Transition t5 = new Transition(v7, v6);
41
    t5.AddTrigger(new CallEvent("suspend operA",
42
                                        1));
43
    Transition t6 = new Transition(v8, v11);
44 t6.AddTrigger(new CallEvent("finish_operA",
                                           2));
45
    t6.ActionBody = delegate() {finish operA(); };
    Transition t\bar{7} = \text{new Transition}(v9, v8);
46
47
    Transition t8 = new Transition(v9, v7);
48 Transition t9 = new Transition(v11,v3);
49} //End of InitFXU
50 public void StartFxu()
51 {
        sml.Enter(); }
52 }
```

Fragments of a detailed execution trace of the exemplary state machine (Fig. 1) are shown below. Time stamps of all log items are omitted for the brevity reasons. The trace was created under condition of two call events occurrences, suspend\_operA() and finish\_operA(). A number in brackets denotes a number of a thread that realizes a considered part of machine execution.

[1] WARN - State diagram < OwnedStateMachine1>: Entered.

[1] INFO - State diagram <OwnedStateMachine1>: Execution of entry-activity started. State is now active.

[1] DEBUG - State diagram <OwnedStateMachine1>: Execution of entry-activity finished.

[7] INFO - Initial pseudostate <OwnedStateMachine1:: Region1 {::UnNamedVertex}>: Entered.

[7] DEBUG - Transition from Initial pseudostate <OwnedStateMachine1::Region1{::UnNamedVertex}> to State <OwnedStateMachine1::Region1::S1>: Traversing started.

[7] INFO - State <OwnedStateMachine1::Region1::S1>: Execution of entry-activity started. State is now active.

(...) //part omitted

[3] DEBUG - State diagram <OwnedStateMachine1>: Completion event <> generated by State <OwnedStateMachine1::Region1::S1> has been dispatched.

[9] DEBUG - State <OwnedStateMachine1::Region1::S1>: Execution of exit-activity started.

[9] INFO - State <OwnedStateMachine1::Region1::S1>: Execution of exit-activity finished. State is now inactive.

[10] DEBUG - Transition from State <OwnedStateMachine1 ::Region1::S1> to Fork <OwnedStateMachine1::Region1 {::UnNamed-Vertex}>: Traversing started.

[10] INFO - Fork <OwnedStateMachine1::Region1 {::UnNamed-Vertex}>: Entered.

[11] DEBUG - Transition from Fork <OwnedStateMachine1 ::Region1 {::UnNamedVertex}> to State <OwnedStateMachine1:: Region1::S2::Region2:: S3\_inS2>: Traversing started.

[11] INFO - State <OwnedStateMachine1::Region1::S2>: Execution of entry-activity started. State is now active.

[11] DEBUG - State <OwnedStateMachine1::Region1 ::S2>: Execution of entry-activity finished. [13] INFO - State <OwnedStateMachine1::Region1::S2>: Execution of do-activity started.

[13] DEBUG - State <OwnedStateMachine1::Region1 ::S2>: Execution of do-activity finished.

[11] INFO - State <OwnedStateMachine1::Region1::S2:: Region2::S3\_inS2>: Execution of entry-activity started. State is now active.

[11] DEBUG - State <OwnedStateMachine1::Region1:: S2::Region2::S3\_inS2>: Execution of entry-activity finished.

[12] DEBUG - Transition from Fork <OwnedStateMachine1 ::Region1 {::UnNamedVertex}> to State <OwnedStateMachine1:: Region1::S2::Region1::S1\_inS2>: Traversing started.

[12] INFO - State <OwnedStateMachine1::Region1::S2:: Region1::S1\_inS2>: Execution of entry-activity started. State is now active.

(...) //part omitted

[3] DEBUG - State diagram <OwnedStateMachine1>: Completion event <> generated by State <OwnedStateMachine1 ::Region1::S2::Region2::S3\_inS2> has been dispatched.

[3] DEBUG - State diagram <OwnedStateMachine1>: Completion event <> generated by State <OwnedStateMachine1 ::Region1::S2::Region1::S1\_inS2> has been dispatched.

[3] DEBUG - State diagram <OwnedStateMachine1>: Call-event <suspend\_operA [ID=1]>. has been dispatched.

[16] DEBUG - State <OwnedStateMachine1::Region1:: S2::Region1::S1 inS2>: Execution of exit-activity started.

[16] INFO - State <OwnedStateMachine1::Region1:: S2::Region1::S1\_inS2>: Execution of exit-activity finished. State is now inactive.

[17] DEBUG - Transition from State <OwnedStateMachine1 ::Region1::S2::Region1::S1\_inS2> to State <OwnedStateMachine1 ::Region1::S2::Region1:: S2\_inS2>: Traversing started.

[17] INFO - State <OwnedStateMachine1::Region1::S2:: Region1::S2\_inS2>: Execution of entry-activity started. State is now active.

[17] DEBUG - State <OwnedStateMachine1::Region1 ::S2::Region1::S2 inS2>: Execution of entry-activity finished.

[18] INFO - State <OwnedStateMachine1::Region1::S2 ::Region1::S2 inS2>: Execution of do-activity started.

[3] DEBUG - State diagram <OwnedStateMachine1>: Call-event <finish\_operA [ID=2]>. has been dispatched.

(...) //part omitted

[22] INFO - Join <OwnedStateMachine1::Region1 {::UnNamed-Vertex}>: Entered.

[22] DEBUG - Transition from Join <OwnedStateMachine1:: Region1{::UnNamedVertex}> to Final state

<OwnedStateMachine1::Region1{::UnNamedVertex}>: Traversing started.

[22] INFO - Final state <OwnedStateMachine1::Region1 {::Un-NamedVertex}>: Entered.

[22] WARN - State diagram < OwnedStateMachine1>: Exiting.

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